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# The Effects of Frame Collisions in 802.11-based Mesh Networks

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## Problem

Wireless network utilization is not efficient

- 802.11 networks are designed for 11 to 54 Mbps
  - 108 Mbps with Turbo Mode (use two channels)
- 802.11-based Mesh Networks can hardly reach few Mbps

Why? --- lack of coordination (no scheduling)

- Uncoordinated nodes generate many collisions
  - Unresponsive traffic flows (UDP) do not slow down
    - Packet dropping
  - Reactive traffic flows (TCP) slow down unfairly
    - Some nodes have better performance than others

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## Who should transmit?

- A receiver can listen to multiple transmitters...
  - ... but not in parallel!
- Collisions happen if wireless nodes are not able to coordinate
- CSMA random access (802.11):
  - A node listens to the channel
  - If the channel is idle, the node transmits with some probability p
- What if two nodes are not in range?
  - Hidden nodes
  - E.g., there is a problem if hidden nodes want to transmit towards the same destination



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## Who should transmit?

- Many works focused on modeling the optimal value for p
  - Graph-theory
  - Markov chains
  - ...
- Many works on experiments are available
  - Simulations
  - Real testbeds
- Results strongly depends on
  - Topology
  - Traffic matrix
  - Protocols (MAC and TRANSPORT)



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### Non-fully backlogged TCP flows





### What if collisions involve uncorrelated traffic? (e.g., data flows and control flows)



- Small control packets collide with big data packets
- This way, overhead (OH) can cause a throughput reduction witch is NOT proportional to the OH traffic!

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### **Overhead Effects**

- Experiment on a 802.11b operational mesh network
- Overhead of 80 kbps (approx. 10 kbps/node)
- Vastly different performance with and without overhead
  - 800 to 1800 kbps degradation
  - 10-20 times injected overhead
  - Heterogeneity of effect mainly due to hidden node presence (*capture effect* and *autorate fallback*)





## Understanding spatial bias

Compounding effect of many factors:

- OH reduces the capacity in a heterogeneous manner
  - Basically depends on hidden nodes and capture effect
- Considering the remaining capacity, MAC and TCP can not cooperate very well...
  - (i) The collision avoidance in medium access protocol induces bistability in which pairs of nodes symmetrically alternate in capturing system resources
  - (ii) The congestion control in transport protocol induces asymmetry in the time spent in each state and favors the one-hop flow
  - (iii) High penalty due to cross-layer effects in terms of loss, delay, and consequently, throughput, in order to re-capture system resources

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(i) 802.11-MAC bi-stability (symmetric effect)



### Due to lack of coordination:

- Bi-stable state: either A transmits and GW is in high backoff, or GW transmits and A is in high backoff
- Success state and fail state alternate



## (ii) Asymmetry induced by TCP

Two nested transport loops and sliding windows



- Asymmetric impact of multipacket capture
- DATA (A, B) burst: ٠ DATA the burst size is limited by: GW Α В TCP window size (GW, B) burst: ٠ DATA self-sustaining loop: Β GW Α TCP ACK are generated ACK





- Node GW incurs small penalty: short duration of fail state but long packet bursts
- Node A incurs high penalty: long duration of fail state and low offered load, high backoff & multiple TCP timeouts





### Does spatial biasing trigger other mechanisms?

Three properties of a mesh:

1- Distributed Approximate Priority:

One-hop nodes have Access Priority

2- Congestion Indication:

Any congested link indicates congestion around the gateway

- gateway airtime must be saturated
- gateway congested  $\rightarrow$  all flows experience congestion
- 3- *Control by proxy*: Enforcing free airtime in the gateway neighborhood gives multi-hop nodes transmission opportunities
  - one-hop controls multi-hop
  - also spatial reuse enhanced

Flow 1 Flow 1 Flow 3 D Flow M E e congestion

Yours

have

Mine



## Counter-bias policy

- All nodes that are directly connected to the gateway should decrease their access probability p
- E.g.: increase the contention window
  - Simple to implement- no overhead or message exchange between nodes
  - Compliant with IEEE 802.11e EDCA
- Or use rate limiting



### Rate limiting at one-hop?



**Idea:** One-hop gives, two-hop takes (*not 1:1*)  $\Rightarrow$  Based on the objective, find a working point



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- Elastic rate limit operates a gateway airtime partitioning
  - Guaranteed one-hop bandwidth
  - Multi-hop bandwidth
  - Unused bandwidth



# How much of the unutilized bandwidth should be reallocated?

- If ALL is reallocated to one-hop nodes ⇒
  No way for multi-hop nodes to rejoin/get the bandwidth back
  - Causes collisions
  - Severe Throughput Imbalance
- If **ZERO** is reallocated to one-hop nodes  $\Rightarrow$  Static
  - Underutilization

**Idea:** make room for **signaling** from multi-hop nodes: just leave a small bandwidth reserved for disadvantaged nodes (a small **gap**):  $B_D \leq \gamma U_{max}$  ( $B_D < < U_{max}$ )



### GAP

### Must leave free air-time at the gateway to let multi-hop nodes signal their demands

- Objectives
  - 1. Ensure minimum rates that would be guaranteed under saturation load conditions
  - 2. Fairly share unused resources among all competing nodes
- Constraints
  - 1. Disadvantaged-flow Signaling Bandwidth  $B_D \le \gamma U_{max}$ 
    - Aggregate
  - 2. Minimum Guaranteed One-hop Rate (1-γ)U<sub>max</sub>
    - Per-node (or aggregate)



## Using the GAP

- Given that
  - *U<sub>max</sub>* is the maximum GW utilization (constant)
  - $B_D$  is reserved to multi-hop traffic (signaling or data)
- Then only multi-hop traffic can drive the GW utilization beyond  $U_{max}$ - $B_D$
- Thus, one-hop nodes can  $\frac{detect}{detect}$  multi-hop traffic by  $\frac{observing}{observing}$  a GW utilization exceeding  $U_{max}$ - $B_D$
- E.g., each one-hop node estimates the GW utilization U(t) and uses AIMD to adjust its rate limiting
  - AIMD based on the aggregate one-hop load U(t) and the threshold  $U_{max}$  - $B_D$

*if U(t) < U<sub>max</sub>-B<sub>D</sub>* Increase rate limit *additively* 

else

Decrease rate limit *multiplicatively* 



## **Analytical Model**



Rate limiting controlled system

**Theorem** : The equilibrium points of the proposed rate control framework are stable

**Corollary**: Perturbations of the equilibrium points of the system are exponentially decaying with time with constant that is based on the equilibrium point



# A fluid simulation of the fluid model

ra

B

r<sub>f</sub>

### Rules of the game

- Time is slotted
- **GW** can sink at most U<sub>max</sub> units/s
- A can push to B only if B and C are idle (*strict priority*)
- Rate limiting at **B** and **C** (*elastic*)
- **B** + **C** aim at not exceeding
  - Umax -GAP units/s

- B and C estimate the load at each slot (*with noise*)
- B's (C's) estimate is allowed to exceed U<sub>max</sub>-GAP only if B (C) is below its guaranteed rate
- **B** and **C** adapt their rate limit at the beginning of the slot
  - Increase or decrease, unless the *minimum guaranteed bandwidth* is reached (→ static default)

r<sub>b</sub>≤ rl

GW

The rate limit **r** is tuned via an AIMD mechanism



### How much GAP?





### GAP is robust to noise Low-pass filtered results





## Is GAP better than scheduling?!

- In a distributed and low-overhead wireless scenario
  - *U(t)* estimates are prone to uncertainty
  - Distributed *U(t)* estimation is not synchronous
  - Centralized U(t) estimation can be delivered in different time instants to different one-hop nodes
  - → distributed scheduling strategies cannot converge under these assumptions
    - →V. Gambiroza, B. Sadeghi, and E. W. Knightly, "End-to-End Performance and Fairness in Multihop Wireless Backhaul Networks," in Proceedings of ACM MOBICOM, 2004
  - Conversely, GAP is robust enough for a distributed implementation and yields fairness

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## Practical issues in GAP implementation

- Distributed (One-hop nodes)
  - Local traffic estimations based on traffic overhearing
  - Prone to large estimate errors
- GW-operated
  - The GW counts the one-hop node traffic
    - Better quality estimate
  - AIMD triggered by GW commands
    - One bit only is needed (increase/decrease AIMD command)
  - Per-node commands
    - Use ACKs to convey commands to each one-hop node
  - Per-aggregate commands
    - Use ACKs or other control messages, e.g., BEACONS to transmit undifferentiated commands
- One-hop good also for UDP upstream
  - UDP downstream is not an issue

NO PACKET OVERHEAD



### Conclusions

- One-hop rate limiting is enough to
  - Drastically reduce collisions
  - Avoid multi-hop starvation
  - Enable fairness
  - Control network throughput
- Elastic rate limiting is needed to better use the available resources
  - GAP protocol
- GAP performs better than scheduling
  - Robust in non-ideal scenarios
- GAP is easy to implement
  - In principle, just include an extra bit in the beacons

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# BACKUP

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### **Experimental Validation**



### **RTS/CTS Enabled**



### GAP is robust to noise (1)





### GAP and fairness





## Simulation (NS2)

GAP vs. IFA (Inter-TAP Fairness Algorithm - scheduled access)

8-branch tree



GAP reaches similar or better performances with no need of signaling message exchange